NAG C Library Function Document

nag_tsa_resid_corr (g13asc)

1 Purpose

nag_tsa_resid_corr (g13asc) is a diagnostic checking routine suitable for use after fitting a Box–Jenkins ARMA model to a univariate time series using nag_tsa_multi_inp_model_estim (g13bec). The residual autocorrelation function is returned along with an estimate of its asymptotic standard errors and correlations. Also, nag_tsa_resid_corr calculates the Box–Ljung portmanteau statistic and its significance level for testing model adequacy.

2 Specification

#include <nag.h>
#include <nagl3.h>

void nag_tsa_resid_corr (Nag_ArimaOrder *arimav, Integer n, const double v[],
                        Integer m, const double par[], Integer narma, double r[],
                        double rc[], Integer *tdrc, double *chi, Integer *df, double *siglev,
                        NagError *fail)

3 Description

Consider the univariate multiplicative autoregressive-moving average model

\[ \phi(B) \Phi(B^s) (W_t - \mu) = \theta(B) \Theta(B^s) \epsilon_t \]  

(1)

where \( W_t \), for \( t = 1, 2, \ldots, n \) denotes a time series and \( \epsilon_t \), for \( t = 1, 2, \ldots, n \) is a residual series assumed to be normally distributed with zero mean and variance \( \sigma^2 (>0) \). The \( \epsilon_t \)'s are also assumed to be uncorrelated. Here \( \mu \) is the overall mean term, \( s \) is the seasonal period and \( B \) is the backward shift operator such that \( B^s W_t = W_{t-s} \). The polynomials in (1) are defined as follows:

\[ \phi(B) = 1 - \phi_1 B - \phi_2 B^2 - \ldots - \phi_p B^p \]

is the non-seasonal autoregressive (AR) operator;

\[ \theta(B) = 1 - \theta_1 B - \theta_2 B^2 - \ldots - \theta_q B^q \]

is the non-seasonal moving average (MA) operator;

\[ \Phi(B^s) = 1 - \phi_1 B^s - \phi_2 B^{2s} - \ldots - \phi_p B^{ps} \]

is the seasonal AR operator; and

\[ \Theta(B^s) = 1 - \theta_1 B^s - \theta_2 B^{2s} - \ldots - \Theta_q B^{qs} \]

is the seasonal MA operator. The model (1) is assumed to be stationary, that is the zeros of \( \phi(B) \) and \( \Phi(B^s) \) are assumed to lie outside the unit circle. The model (1) is also assumed to be invertible, that is the zeros of \( \theta(B) \) and \( \Theta(B^s) \) are assumed to lie outside the unit circle. When both \( \Phi(B^s) \) and \( \Theta(B^s) \) are absent from the model, that is when \( P = Q = 0 \), then the model is said to be non-seasonal.

The estimated residual autocorrelation coefficient at lag \( l \), \( \hat{r}_l \), is computed as:

\[ \hat{r}_l = \frac{\sum_{t=l+1}^{n} (\epsilon_{t-l} - \bar{\epsilon})(\epsilon_t - \bar{\epsilon})}{\sum_{t=1}^{n} (\epsilon_t - \bar{\epsilon})^2}, \quad l = 1, 2, \ldots \]

where \( \hat{\epsilon}_t \) denotes an estimate of the \( t \)th residual, \( \epsilon_t \), and \( \bar{\epsilon} = \sum_{t=1}^{n} \hat{\epsilon}_t / n \). A portmanteau statistic, \( Q_{(m)} \), is calculated from the formula (see Box and Ljung (1978)): 

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\[ Q(m) = n(n + 2) \sum_{l=1}^{m} \hat{r}_l^2/(n - l) \]

where \( m \) denotes the number of residual autocorrelations computed. (Advice on the choice of \( m \) is given in Section 6.) Under the hypothesis of model adequacy, \( Q(m) \) has an asymptotic \( \chi^2 \) distribution on \( m - p - q - P - Q \) degrees of freedom. Let \( \hat{r}_l^2 = (\hat{r}_1, \hat{r}_2, \ldots, \hat{r}_m) \) then the variance-covariance matrix of \( \hat{r} \) is given by:

\[ \text{Var}(\hat{r}) = [I_m - X(X^T X)^{-1} X^T]/n. \]

The construction of the matrix \( X \) is discussed in McLeod (1978). (Note that the mean, \( \mu \), and the residual variance, \( \sigma^2 \), play no part in calculating \( \text{Var}(\hat{r}) \) and therefore are not required as input to nag_tsa_resid_corr.)

4 Parameters

1. \textbf{arimav} = Nag_ArimaOrder *

   Pointer to structure of type \textbf{Nag_ArimaOrder} with the following members:

   \begin{itemize}
   \item \textbf{p} – Integer \hspace{1cm} \textit{Input}
   \item \textbf{d} – Integer \hspace{1cm} \textit{Input}
   \item \textbf{q} – Integer \hspace{1cm} \textit{Input}
   \item \textbf{bigp} – Integer \hspace{1cm} \textit{Input}
   \item \textbf{bigd} – Integer \hspace{1cm} \textit{Input}
   \item \textbf{bigq} – Integer \hspace{1cm} \textit{Input}
   \item \textbf{s} – Integer \hspace{1cm} \textit{Input}
   \end{itemize}

   These seven members of \textbf{arimav} must specify the orders vector \((p, d, q, P, D, Q, s)\), respectively, of the ARIMA model for the output noise component.

   \( p, q, P \) and \( Q \) refer, respectively, to the number of autoregressive \((\phi)\), moving average \((\theta)\), seasonal autoregressive \((\Phi)\) and seasonal moving average \((\Theta)\) parameters.

   \( d, D \) and \( s \) refer, respectively, to the order of non-seasonal differencing, the order of seasonal differencing and the seasonal period.

   Constraints:

   \[ p, q, \textbf{bigp}, \textbf{bigq}, s \geq 0, \]

   \[ p + q + \textbf{bigp} + \textbf{bigq} > 0, \]

   if \( s = 0 \), then \( \textbf{bigp} = 0 \) and \( \textbf{bigq} = 0 \).

2. \textbf{n} – Integer \hspace{1cm} \textit{Input}

   \textit{On entry:} the number of observations in the residual series, \( n \).

   \textit{Constraint:} \( n \geq 3 \).

3. \textbf{v[n]} – const double \hspace{1cm} \textit{Input}

   \textit{On entry:} \( v(t) \) must contain an estimate of \( \epsilon_t \), for \( t = 1, 2, \ldots, n \).

   \textit{Constraint:} \( v \) must contain at least two distinct elements.

4. \textbf{m} – Integer \hspace{1cm} \textit{Input}

   \textit{On entry:} the value of \( m \), the number of residual autocorrelations to be computed. See Section 6 for advice on the value of \( m \).

   \textit{Constraint:} \( \textbf{narma} < m < n \).
5: par[narma] – const double

Input

On entry: the parameter estimates in the order \( \phi_1, \phi_2, \ldots, \phi_p, \theta_1, \theta_2, \ldots, \theta_q, \Phi_1, \Phi_2, \ldots, \Phi_P, \Theta_1, \Theta_2, \ldots, \Theta_Q \) only.

Constraint: the elements in par must satisfy the stationarity and invertibility conditions.

6: narma – Integer

Input

On entry: the number of ARMA parameters, \( \phi, \theta, \Phi \) and \( \Theta \) parameters, i.e., \( \text{narma} = p + q + P + Q \).

Constraint: \( \text{narma} = \text{arima.p} + \text{arima.q} + \text{arima.bigp} + \text{arima.bigq} \).

7: r[m] – double

Output

On exit: an estimate of the residual autocorrelation coefficient at lag \( l \), for \( l = 1, 2, \ldots, m \). If \( \text{fail.code} = \text{NE_G13AS_ZERO_VAR} \) on exit then all elements of \( r \) are set to zero.

8: rc[m][tdrc] – double

Output

On exit: the estimated standard errors and correlations of the elements in the array \( r \). The correlation between \( r[i-1] \) and \( r[j-1] \) is returned as \( \text{rc}[i-1][j-1] \) except that if \( i = j \) then \( \text{rc}[i-1][j-1] \) contains the standard error of \( r[i-1] \). If on exit, \( \text{fail.code} = \text{NE_G13AS_FACT} \) or \( \text{NE_G13AS_DIAG} \), then all off-diagonal elements of \( \text{rc} \) are set to zero and all diagonal elements are set to \( 1/\sqrt{n} \).

9: tdrd – Integer

Input

On entry: the second dimension of the array \( \text{rc} \) as declared in the function from which \( \text{tfg_tsa_resid_corr} \) is called.

Constraint: \( \text{tdrd} \geq m \).

10: chi – double *

Output

On exit: the value of the portmanteau statistic, \( Q(m) \). If \( \text{fail.code} = \text{NE_G13AS_ZERO_VAR} \) on exit then \( \text{chi} \) is returned as zero.

11: df – Integer *

Output

On exit: the number of degrees of freedom of \( \text{chi} \).

12: siglev – double *

Output

On exit: the significance level of \( \text{chi} \) based on \( \text{idf} \) degrees of freedom. If \( \text{fail.code} = \text{NE_G13AS_ZERO_VAR} \) on exit then \( \text{siglev} \) is returned as one.

13: fail – NagError *

Input/Output

The NAG error parameter (see the Essential Introduction).

5 Error Indicators and Warnings

\( \text{NE_ARIMA_INPUT} \)

On entry, \( \text{arima.p} = \text{<value>} \), \( \text{arima.d} = \text{<value>} \), \( \text{arima.q} = \text{<value>} \), \( \text{arima.bigp} = \text{<value>} \), \( \text{arima.bigd} = \text{<value>} \), \( \text{arima.bigq} = \text{<value>} \) and \( \text{arima.s} = \text{<value>} \).

Constraints on the members of \( \text{arima} \) are:

\( p, q, \text{bigp}, \text{bigq}, s \geq 0, p + q + \text{bigp} + \text{bigq} > 0, \) if \( s = 0 \), then \( \text{bigp} = 0 \) and \( \text{bigq} = 0 \).
NE_INPUT_NARMA
On entry, \( \text{arima} . p = \langle \text{value} \rangle, \text{arima} . q = \langle \text{value} \rangle, \text{arima} . \text{bigp} = \langle \text{value} \rangle, \text{arima} . \text{bigq} = \langle \text{value} \rangle \)
while \( \text{narma} = \langle \text{value} \rangle \).
Constraint: \( \text{narma} = \text{arima} . p + \text{arima} . q + \text{arima} . \text{bigp} + \text{arima} . \text{bigq} \).

NE_INT_3
On entry, \( \text{m} = \langle \text{value} \rangle, \text{n} = \langle \text{value} \rangle, \text{narma} = \langle \text{value} \rangle \).
Constraint: \( \text{narma} < \text{m} < \text{n} \).

NE_2_INT_ARG_LT
On entry, \( \text{tdrc} = \langle \text{value} \rangle \) while \( \text{m} = \langle \text{value} \rangle \). These parameters must satisfy \( \text{tdrc} \geq \text{m} \).

NE_INT_ARG_LT
On entry, \( \text{n} \) must not be less than 3: \( \text{n} = \langle \text{value} \rangle \).

NE_G13AS_AR
On entry, the autoregressive (or moving average) parameters are extremely close to or outside the stationarity (or invertibility) region. To proceed, the user must supply different parameter estimates in the array \( \text{par} \).

NE_G13ASZERO_VAR
On entry, the residuals are practically identical giving zero (or near zero) variance. In this case \( \text{chi} \) is set to zero, \( \text{siglev} \) to one and all the elements of \( \text{r} \) set to zero.

NE_G13AS_ITER
This is an unlikely exit brought about by an excessive number of iterations being needed to evaluate the zeros of the AR or MA polynomials. All output parameters are undefined.

NE_G13AS_FACT
On entry, one or more of the AR operators has a factor in common with one or more of the MA operators. To proceed, this common factor must be deleted from the model. In this case, the off-diagonal elements of \( \text{rc} \) are returned as zero and the diagonal elements set to \( 1/\sqrt{n} \). All other output quantities will be correct.

NE_G13AS_DIAG
This is an unlikely exit. At least one of the diagonal elements of \( \text{rc} \) was found to be either negative or zero. In this case all off-diagonal elements of \( \text{rc} \) are returned as zero and all diagonal elements of \( \text{rc} \) set to \( 1/\sqrt{n} \).

NE_ALLOC_FAIL
Memory allocation failed.

NE_INTERNAL_ERROR
An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please consult NAG for assistance.

6 Further Comments
6.1 Accuracy
The computations are believed to be stable.
6.2 References


6.3 Timing
The time taken by the routine depends upon the number of residual autocorrelations to be computed, \( m \).

6.4 Choice of \( m \)
The number of residual autocorrelations to be computed, \( m \) should be chosen to ensure that when the ARMA model (1) is written as either an infinite order autoregressive process:

\[
W_t - \mu = \sum_{j=1}^{\infty} \pi_j(W_{t-j} - \mu) + \epsilon_t
\]
or as an infinite order moving average process:

\[
W_t - \mu = \sum_{j=1}^{\infty} \psi_j \epsilon_{t-j} + \epsilon_t
\]

then the two sequences \( \{\pi_1, \pi_2, \ldots\} \) and \( \{\psi_1, \psi_2, \ldots\} \) are such that \( \pi_j \) and \( \psi_j \) are approximately zero for \( j > m \). An over-estimate of \( m \) is therefore preferable to an under-estimate of \( m \). In many instances the choice \( m = 10 \) will suffice. In practice, to be on the safe side, the user should try setting \( m = 20 \).

6.5 Approximate Standard Errors
When fail.code is returned as **NE_G13AS_FACT** or **NE_G13AS_DIAG** all the standard errors in re are set to \( 1/\sqrt{n} \). This is the asymptotic standard error of \( \hat{\epsilon} \) when all the autoregressive and moving average parameters are assumed to be known rather than estimated.

7 See Also
None.

8 Example
A program to fit an ARIMA(1,1,2) model to a series of 30 observations. 10 residual autocorrelations are computed.

8.1 Program Text
/* nag_tsa_resid_corr (g13asc) Example Program. *
 * Copyright 2000 Numerical Algorithms Group.
 * * Mark 6, 2000.
 */

#include <stdio.h>
#include <nag.h>
#include <nag_stdlib.h>
#include <naggl3.h>
#include <nagx04.h>
```c
int main (void)
{
    double chi, df, objf, *par=0, *r=0, *rc=0, *res, s, *sd=0, siglev;
    double *x=0;
    Integer i, idf, m, *mr=0, narma, npar, nres;
    Integer nx, nseries;
    Integer exit_status=0;
    Nag_ArimaOrder arimav;
    Nag_TransfOrder transfv;
    Nag_G13_Opt options;
    NagError fail;

    INIT_FAIL(fail);
    Vprintf("g13asc Example Program Results\n\n");

    /* Skip heading in data file */
    Vscanf("%*[\n"]);

    Vscanf("%ld%*[\n"] , &nx);
    if (!(!x = NAG_ALLOC(nx, double))
        || (!mr = NAG_ALLOC(7, Integer)))
    {
        Vprintf("Allocation failure\n");
        exit_status = -1;
        goto END;
    }

    for (i = 1; i <= nx; ++i)
        Vscanf("%lf", &x[i - 1]);
    Vscanf("%*[\n"]);
    for (i = 1; i <= 7; ++i)
        Vscanf("%ld", &mr[i - 1]);
    Vscanf("%*[\n"]);

    if (!(!par = NAG_ALLOC(npar, double))
        || (!sd = NAG_ALLOC(npar, double)))
    {
        Vprintf("Allocation failure\n");
        exit_status = -1;
        goto END;
    }

    for (i = 1; i <= npar; ++i)
    par[i - 1] = 0.0;

    nseries = 1;
    arimav.p = mr[0];
    arimav.d = mr[1];
    arimav.q = mr[2];
    arimav.bigr = mr[3] ;
    arimav.bigd = mr[4] ;
    arimav.bigq = mr[5] ;
    arimav.s = mr[6] ;
    g13bxc(&options);
    g13byc(nseries, &transf, &fail);
    g13bec(&arimav, nseries, &transf, par, npar, nx, x, nseries, sd, &s, &objf, &df, &options, &fail);
    nres = options.lenres;
    res = options.res;
```
if (fail.code != NE_NOERROR)
{
    Vprintf("Error from gl3bec.\n\n", fail.message);
    exit_status = 1;
    goto END;
}

m = 10;
if (! (r = NAG_ALLOC(m, double))
    || ! (rc = NAG_ALLOC(m*m, double))
{
    Vprintf("Allocation failure\n");
    exit_status = -1;
    goto END;
}

gl3asc(arimav, nres, res, m, par, narma, r, rc, m, &chi, &idf, &siglev, &fail);
if (fail.code != NE_NOERROR)
{
    Vprintf("Error from gl3asc.\n\n", fail.message);
    exit_status = 1;
    goto END;
}
Vprintf("\n\nRESIDUAL AUTOCORRELATION FUNCTION\n-------------------------------------
\n\n");
Vprintf("R(k)         ");
for (i=0; i<m; i++)
    Vprintf("%10.3f", r[i]);
Vprintf("\n\nStandard Error      ");
for (i=0; i<m; i++)
    Vprintf("%10.3f", rc[10*i+i]);
Vprintf("\n\n");
g13xzcc(&options);

END:
    if (x) NAG_FREE(x);
    if (mr) NAG_FREE(mr);
    if (par) NAG_FREE(par);
    if (sd) NAG_FREE(sd);
    if (r) NAG_FREE(r);
    if (rc) NAG_FREE(rc);
    return exit_status;
}

8.2 Program Data

g13asc Example Program Data
30 : nx, length of the time series
-217 -177 -166 -136 -110 -95 -64 -37
-14 -25 -51 -62 -73 -88 -113 -120
-83 -33 -19 21 17 44 44 78
  88 122 126 114 85 64  : End of time series
l l 2 0 0 0 0  : mr, orders vector of the model

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8.3 Program Results

gl3asc Example Program Results

Parameters to gl3bec

nseries.................. 1

criteria................. Nag_Exact cfixed.................. FALSE
alpha.................... 1.00e-02 beta..................... 1.00e+01
delta..................... 1.00e+03 gamma.................... 1.00e-07
print_level.............. Nag_Soln
outfile.................. stdout

The number of iterations carried out is 15

The final values of the parameters and their standard deviations are

<table>
<thead>
<tr>
<th>i</th>
<th>para[i]</th>
<th>sd</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>-0.094096</td>
<td>0.361543</td>
</tr>
<tr>
<td>2</td>
<td>-0.579152</td>
<td>0.295984</td>
</tr>
<tr>
<td>3</td>
<td>-0.611889</td>
<td>0.182241</td>
</tr>
<tr>
<td>4</td>
<td>9.932425</td>
<td>7.050207</td>
</tr>
</tbody>
</table>

The residual sum of squares = 9.436281e+03

The objective function = 9.762154e+03

The degrees of freedom = 25.00

RESIDUAL AUTOCORRELATION FUNCTION

<table>
<thead>
<tr>
<th>R(k)</th>
<th>0.030</th>
<th>0.026</th>
<th>-0.039</th>
<th>0.043</th>
<th>-0.129</th>
<th>-0.062</th>
<th>-0.218</th>
</tr>
</thead>
<tbody>
<tr>
<td>-0.105</td>
<td>-0.024</td>
<td>-0.072</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Standard Error

<table>
<thead>
<tr>
<th>0.011</th>
<th>0.116</th>
<th>0.122</th>
<th>0.147</th>
<th>0.171</th>
<th>0.171</th>
<th>0.179</th>
</tr>
</thead>
<tbody>
<tr>
<td>0.182</td>
<td>0.182</td>
<td>0.184</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>