NAG C Library Function Document

nag_1d_cheb_eval2 (e02akc)

1 Purpose
nag_1d_cheb_eval2 (e02akc) evaluates a polynomial from its Chebyshev-series representation, allowing an arbitrary index increment for accessing the array of coefficients.

2 Specification

```c
void nag_1d_cheb_eval2 (Integer n, double xmin, double xmax, const double a[],
    Integer ia1, double x, double *result, NagError *fail)
```

3 Description

If supplied with the coefficients \(a_i\), for \(i = 0, 1, \ldots, n\), of a polynomial \(p(\tilde{x})\) of degree \(n\), where
\[
p(\tilde{x}) = \frac{1}{2} a_0 + a_1 T_1(\tilde{x}) + \cdots + a_n T_n(\tilde{x}),
\]
\(nag_1d\_cheb\_eval2\) (e02akc) returns the value of \(p(\tilde{x})\) at a user-specified value of the variable \(x\). Here \(T_j(\tilde{x})\) denotes the Chebyshev polynomial of the first kind of degree \(j\) with argument \(\tilde{x}\). It is assumed that the independent variable \(\tilde{x}\) in the interval \([-1, +1]\) was obtained from the user’s original variable \(x\) in the interval \([x_{\text{min}}, x_{\text{max}}]\) by the linear transformation
\[
\tilde{x} = \frac{2x - (x_{\text{max}} + x_{\text{min}})}{x_{\text{max}} - x_{\text{min}}}.
\]
The coefficients \(a_i\) may be supplied in the array \(a\), with any increment between the indices of array elements which contain successive coefficients. This enables the function to be used in surface fitting and other applications, in which the array might have two or more dimensions.

The method employed is based upon the three-term recurrence relation due to Clenshaw (see Clenshaw (1955)), with modifications due to Reinsch and Gentleman (see Gentleman (1969)). For further details of the algorithm and its use see Cox (1973) and Cox and Hayes (1973).

4 References


Cox M G (1973) A data-fitting package for the non-specialist user NPL Report NAC 40 National Physical Laboratory

Cox M G and Hayes J G (1973) Curve fitting: a guide and suite of algorithms for the non-specialist user NPL Report NAC26 National Physical Laboratory


5 Parameters

1: \(n\) – Integer

\(On\ entry: n\), the degree of the given polynomial \(p(\tilde{x})\).

\(Constraint: n \geq 0.\)
2: \( \text{xmin} \) – double \hspace{1cm} \text{Input}
3: \( \text{xmax} \) – double \hspace{1cm} \text{Input}

*On entry*: the lower and upper end-points respectively of the interval \([x_{\text{min}}, x_{\text{max}}]\). The Chebyshev-series representation is in terms of the normalised variable \( \bar{x} \), where

\[
\bar{x} = \frac{2x - (x_{\text{max}} + x_{\text{min}})}{x_{\text{max}} - x_{\text{min}}}. 
\]

*Constraint*: \( \text{xmin} < \text{xmax} \).

4: \( \text{a}[\text{dim}] \) – const double \hspace{1cm} \text{Input}

*Note*: the dimension, \( \text{dim} \), of the array \( \text{a} \) must be at least \( n \times \text{ia1} + 1 \).

*On entry*: the Chebyshev coefficients of the polynomial \( p(\bar{x}) \). Specifically, element \( i \times \text{ia1} \) must contain the coefficient \( a_i \), for \( i = 0, 1, \ldots, n \). Only these \( n + 1 \) elements will be accessed.

5: \( \text{ia1} \) – Integer \hspace{1cm} \text{Input}

*On entry*: the index increment of \( \text{a} \). Most frequently, the Chebyshev coefficients are stored in adjacent elements of \( \text{a} \), and \( \text{ia1} \) must be set to 1. However, if, for example, they are stored in \( \text{a}[0], \text{a}[3], \text{a}[6], \ldots \), then the value of \( \text{ia1} \) must be 3.

*Constraint*: \( \text{ia1} \geq 1 \).

6: \( \text{x} \) – double \hspace{1cm} \text{Input}

*On entry*: the argument \( x \) at which the polynomial is to be evaluated.

*Constraint*: \( \text{xmin} \leq x \leq \text{xmax} \).

7: \( \text{result} \) – double * \hspace{1cm} \text{Output}

*On exit*: the value of the polynomial \( p(\bar{x}) \).

8: \( \text{fail} \) – NagError * \hspace{1cm} \text{Input/Output}

The NAG error parameter (see the Essential Introduction).

### 6 Error Indicators and Warnings

**NE_INT**

On entry, \( n = \langle \text{value} \rangle \).

*Constraint*: \( n \geq 0 \).

On entry, \( \text{ia1} = \langle \text{value} \rangle \).

*Constraint*: \( \text{ia1} \geq 1 \).

**NE_REAL_2**

On entry, \( \text{xmax} \leq \text{xmin} \): \( \text{xmax} = \langle \text{value} \rangle \), \( \text{xmin} = \langle \text{value} \rangle \).

**NE_REAL_3**

On entry, \( \text{x} \) does not lie in \([\text{xmin}, \text{xmax}]\): \( \text{x} = \langle \text{value} \rangle \), \( \text{xmin} = \langle \text{value} \rangle \), \( \text{xmax} = \langle \text{value} \rangle \).

**NE_BAD_PARAM**

On entry, parameter \( \langle \text{value} \rangle \) had an illegal value.

**NE_INTERNAL_ERROR**

An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please consult NAG for assistance.
7 Accuracy

The rounding errors are such that the computed value of the polynomial is exact for a slightly perturbed set of coefficients $a_i + \delta a_i$. The ratio of the sum of the absolute values of the $\delta a_i$ to the sum of the absolute values of the $a_i$ is less than a small multiple of $(n + 1) \times \text{machine precision}$.

8 Further Comments

The time taken is approximately proportional to $n + 1$.

9 Example

Suppose a polynomial has been computed in Chebyshev-series form to fit data over the interval $[-0.5, 2.5]$. The following program evaluates the polynomial at 4 equally spaced points over the interval. (For the purposes of this example, $\text{xmin}$, $\text{xmax}$ and the Chebyshev coefficients are supplied. Normally a program would first read in or generate data and compute the fitted polynomial.)

9.1 Program Text

```c
/* nag_1d_cheb_eval2 (e02akc) Example Program. */
/* Copyright 2001 Numerical Algorithms Group. */
/* * Mark 7, 2001. */

#include <stdio.h>
#include <nag.h>
#include <nag_stdlib.h>
#include <nage02.h>

int main(void)
{
    /* Initialized data */
    const double xmin = -0.5;
    const double xmax = 2.5;
    const double a[7] = { 2.53213, 1.13032, 0.2715, 0.04434, 0.00547, 5.4e-4, 4e-5 };

    /* Scalars */
    double p, x;
    Integer exit_status, i, m, n, one;
    NagError fail;

    INIT_FAIL(fail);
    exit_status = 0;
    Vprintf("e02akc Example Program Results\n");
    n = 6;
    one = 1;

    Vprintf("\n");
    Vprintf(" i Argument Value of polynomial\n");
    m = 4;
    for (i = 1; i <= m; ++i)
    {
        x = (xmin * (double) (m - i) + xmax * (double) (i - 1)) / (double) (m - 1);
        e02akc(n, xmin, xmax, a, one, x, &p, &fail);
        if (fail.code != NE_NOERROR)
        {
            Vprintf("Error from e02akc.\n", fail.message);
            exit_status = 1;
            goto END;
        }
        Vprintf("%4ld%10.4f %9.4f\n", i, x, p);
    }
```

[NP3645/7] e02akc.3
9.2 Program Data

None.

9.3 Program Results

e02akc Example Program Results

<table>
<thead>
<tr>
<th>i</th>
<th>Argument</th>
<th>Value of polynomial</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>-0.5000</td>
<td>0.3679</td>
</tr>
<tr>
<td>2</td>
<td>0.5000</td>
<td>0.7165</td>
</tr>
<tr>
<td>3</td>
<td>1.5000</td>
<td>1.3956</td>
</tr>
<tr>
<td>4</td>
<td>2.5000</td>
<td>2.7183</td>
</tr>
</tbody>
</table>