NAG C Library Function Document

nag_pde_parab_1d_euler_exact (d03pxc)

1 Purpose

nag_pde_parab_1d_euler_exact (d03pxc) calculates a numerical flux function using an Exact Riemann Solver for the Euler equations in conservative form. It is designed primarily for use with the upwind discretisation schemes nag_pde_parab_1d_cd (d03pfc), nag_pde_parab_1d_cd_ode (d03plc) or nag_pde_parab_1d_cd_ode_remesh (d03psc), but may also be applicable to other conservative upwind schemes requiring numerical flux functions.

2 Specification

void nag_pde_parab_1d_euler_exact (const double *uleft[], const double *uright[], double gamma, double tol, Integer niter, double flux[], Nag_D03_Save *saved, NagError *fail)

3 Description

nag_pde_parab_1d_euler_exact (d03pxc) calculates a numerical flux function at a single spatial point using an Exact Riemann Solver (see Toro (1996) and Toro (1989)) for the Euler equations (for a perfect gas) in conservative form. The user must supply the left and right solution values at the point where the numerical flux is required, i.e., the initial left and right states of the Riemann problem defined below. In nag_pde_parab_1d_cd (d03pfc), nag_pde_parab_1d_cd_ode (d03plc) and nag_pde_parab_1d_cd_ode_remesh (d03psc), the left and right solution values are derived automatically from the solution values at adjacent spatial points and supplied to the function argument numflx from which the user may call nag_pde_parab_1d_euler_exact (d03pxc).

The Euler equations for a perfect gas in conservative form are:

\[
\frac{\partial U}{\partial t} + \frac{\partial F}{\partial x} = 0,
\]

with

\[
U = \begin{bmatrix}
\rho \\
m \\
e
\end{bmatrix}
\]

and

\[
F = \begin{bmatrix}
\frac{m^2}{p} + (\gamma - 1)\left( e - \frac{m^2}{2p} \right) \\
\frac{me}{p} + \frac{m}{p}(\gamma - 1)\left( e - \frac{m^2}{2p} \right)
\end{bmatrix},
\]

where \(\rho\) is the density, \(m\) is the momentum, \(e\) is the specific total energy and \(\gamma\) is the (constant) ratio of specific heats. The pressure \(p\) is given by

\[
p = (\gamma - 1)\left( e - \frac{\rho u^2}{2} \right),
\]

where \(u = m/\rho\) is the velocity.

The function calculates the numerical flux function \(F(U_L, U_R) = F(U^*(U_L, U_R))\), where \(U = U_L\) and \(U = U_R\) are the left and right solution values, and \(U^*(U_L, U_R)\) is the intermediate state \(\omega(0)\) arising from the similarity solution \(U(y, t) = \omega(y/t)\) of the Riemann problem defined by

\[
\frac{\partial U}{\partial t} + \frac{\partial F}{\partial y} = 0,
\]

with \(U\) and \(F\) as in (2), and initial piecewise constant values \(U = U_L\) for \(y < 0\) and \(U = U_R\) for \(y > 0\). The spatial domain is \(-\infty < y < \infty\), where \(y = 0\) is the point at which the numerical flux is required.

The algorithm is termed an Exact Riemann Solver although it does in fact calculate an approximate solution to a true Riemann problem, as opposed to an Approximate Riemann Solver which involves some form of alternative modelling of the Riemann problem. The approximation part of the Exact Riemann
Solver is a Newton–Raphson iterative procedure to calculate the pressure, and the user must supply a tolerance \( \text{tol} \) and a maximum number of iterations \( \text{niter} \). Default values for these parameters can be chosen.

A solution cannot be found by this function if there is a vacuum state in the Riemann problem (loosely characterised by zero density), or if such a state is generated by the interaction of two non-vacuum data states. In this case a Riemann solver which can handle vacuum states has to be used (see Toro (1996)).

4 References

5 Parameters
1: \( \text{uleft}[3] \) – const double
   \( \text{Input} \)
   \( \text{On entry:} \ \text{uleft}[i - 1] \) must contain the left value of the component \( U_i \) for \( i = 1, 2, 3 \). That is, \( \text{uleft}[0] \) must contain the left value of \( \rho \), \( \text{uleft}[1] \) must contain the left value of \( m \) and \( \text{uleft}[2] \) must contain the left value of \( e \).

2: \( \text{uright}[3] \) – const double
   \( \text{Input} \)
   \( \text{On entry:} \ \text{uright}[i - 1] \) must contain the right value of the component \( U_i \) for \( i = 1, 2, 3 \). That is, \( \text{uright}[0] \) must contain the right value of \( \rho \), \( \text{uright}[1] \) must contain the right value of \( m \) and \( \text{uright}[2] \) must contain the right value of \( e \).

3: \( \gamma \) – double
   \( \text{Input} \)
   \( \text{On entry:} \) the ratio of specific heats \( \gamma \).
   \( \text{Constraint:} \ \gamma > 0.0 \).

4: \( \text{tol} \) – double
   \( \text{Input} \)
   \( \text{On entry:} \) the tolerance to be used in the Newton-Raphson procedure to calculate the pressure. If \( \text{tol} \) is set to zero then the default value of \( 1.0 \times 10^{-6} \) is used.
   \( \text{Constraint:} \ \text{tol} \geq 0.0 \).

5: \( \text{niter} \) – Integer
   \( \text{Input} \)
   \( \text{On entry:} \) the maximum number of Newton-Raphson iterations allowed. If \( \text{niter} \) is set to zero then the default value of 20 is used.
   \( \text{Constraint:} \ \text{niter} \geq 0 \).

6: \( \text{flux}[3] \) – double
   \( \text{Output} \)
   \( \text{On exit:} \ \text{flux}[i - 1] \) contains the numerical flux component \( \tilde{F}_i \) for \( i = 1, 2, 3 \).

7: \( \text{saved} \) – Nag_D03_Save *
   \( \text{Input/Output} \)
   \( \text{Note:} \ \text{saved} \) is a NAG defined structure. See Section 2.2.1.1 of the Essential Introduction.
   \( \text{On entry:} \) data concerning the computation required by nag_pde_parab_1d_euler_exact (d03pxc) and passed through to numfix from one of the integrator functions nag_pde_parab_1d_cd (d03pfc), nag_pde_parab_1d_cd_ode (d03ple), or nag_pde_parab_1d_cd_ode_remesh (d03psc).
   \( \text{On exit:} \) modified data required by the integrator function.
6 Error Indicators and Warnings

**NE_INT**
On entry, \(niter = \langle \text{value} \rangle\).
Constraint: \(niter \geq 0\).

**NE_ITER_FAIL_CONV**
Newton-Raphson iteration failed to converge.

**NE_REAL**
Right pressure value \(pr < 0.0\): \(pr = \langle \text{value} \rangle\).
Left pressure value \(pl < 0.0\): \(pl = \langle \text{value} \rangle\).
On entry, \(\text{uright}[0] < 0.0\): \(\text{uright}[0] = \langle \text{value} \rangle\).
On entry, \(\text{uleft}[0] < 0.0\): \(\text{uleft}[0] = \langle \text{value} \rangle\).
On entry, \(\text{tol} = \langle \text{value} \rangle\).
Constraint: \(\text{tol} \geq 0.0\).
On entry, \(\text{gamma} = \langle \text{value} \rangle\).
Constraint: \(\text{gamma} > 0.0\).

**NE_VACUUM**
A vacuum condition has been detected.

**NE_ALLOC_FAIL**
Memory allocation failed.

**NE_BAD_PARAM**
On entry, parameter \(\langle \text{value} \rangle\) had an illegal value.

**NE_INTERNAL_ERROR**
An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please consult NAG for assistance.

7 Accuracy
The algorithm is exact apart from the calculation of the pressure which uses a Newton-Raphson iterative procedure, the accuracy of which is controlled by the parameter \(\text{tol}\). In some cases the initial guess for the Newton-Raphson procedure is exact and no further iterations are required.

8 Further Comments
The function must only be used to calculate the numerical flux for the Euler equations in exactly the form given by (2), with \(\text{uleft}[i - 1]\) and \(\text{uright}[i - 1]\) containing the left and right values of \(\rho, m\) and \(e\) for \(i = 1, 2, 3\) respectively.

For some problems the function may fail or be highly inefficient in comparison with an Approximate Riemann Solver (e.g., nag_pde_parab_1d_euler_roe (d03puc), nag_pde_parab_1d_euler_osher (d03pvc) or nag_pde_parab_1d_euler_hll (d03pwc)). Hence it is advisable to try more than one Riemann solver and to compare the performance and the results.
The time taken is independent of all input parameters other than tol.

9 Example

This example uses nag_pde_parab_1d_cd_ode (d03plc) and nag_pde_parab_1d_euler_exact (d03pxc) to solve the Euler equations in the domain $0 \leq x \leq 1$ for $0 < t \leq 0.035$ with initial conditions for the primitive variables $\rho(x,t)$, $u(x,t)$ and $p(x,t)$ given by

$$
\begin{align*}
\rho(x,0) &= 5.99924, \\ u(x,0) &= 19.5975, \\ p(x,0) &= 460.894, & \text{for } x < 0.5, \\
\rho(x,0) &= 5.99242, \\ u(x,0) &= -6.19633, \\ p(x,0) &= 46.095, & \text{for } x > 0.5.
\end{align*}
$$

This test problem is taken from Toro (1996) and its solution represents the collision of two strong shocks travelling in opposite directions, consisting of a left facing shock (travelling slowly to the right), a right travelling contact discontinuity and a right travelling shock wave. There is an exact solution to this problem (see Toro (1996)) but the calculation is lengthy and has therefore been omitted.

9.1 Program Text

/* nag_pde_parab_1d_euler_exact (d03pxc) Example Program. *
 * Copyright 2001 Numerical Algorithms Group. *
 * * Mark 7, 2001. */

#include <stdio.h>
#include <nag.h>
#include <nag_stdlib.h>
#include <nagd03.h>
#include <nagx01.h>
#include <math.h>

/* Structure to communicate with user-supplied function arguments */
struct user
{
    double elo, ero, rlo, rro, ulo, uro, gamma;
};

static void bndary(Integer, Integer, double, const double[ ],
                    const double[ ], Integer, const double[ ],
                    const double[ ], Integer, double[ ], Integer *
                    Nag_Comm *);

static void numflx(Integer, double, double, Integer, const double[ ],
                    const double[ ], const double[ ], double[ ], Integer *
                    Nag_Comm *, Nag_D03_Save *);

#define U(I,J) u[npde*((J)-1)+(I)-1]
#define UE(I,J) ue[npde*((J)-1)+(I)-1]

int main(void)
{
    const Integer npde=3, npts=141, ncode=0, nxi=0, negn=npde*npts+ncode,
    lisave=negl+24, intpts=9, nwkres=npde*(2*npts+3*npde+32)+7*npts+4,
    lenode=9*negl+50, mlu=3*npde-1, lrsave=(3*mlu+1)*negl+nwkres+lenode;
    double d, p, tout, ts, v;
    Integer exit_status, i, ind, itask, itol, itrace, k;
    double *algopt=0, *atol=0, *rtol=0, *u=0,
    *ue=0, *rsave=0, *x=0, *xi=0;
    Integer *isave=0;
    NagError fail;
    Nag_Comm comm;
    Nag_D03_Save saved;
    struct user data;
    /* Allocate memory */
if (!(algopt = NAG_ALLOC(30, double)) ||
    !(atol = NAG_ALLOC(1, double)) ||
    !(rtol = NAG_ALLOC(1, double)) ||
    !(u = NAG_ALLOC(npde*npts, double)) ||
    !(ue = NAG_ALLOC(npde*intpts, double)) ||
    !(rsave = NAG_ALLOC(lrsave, double)) ||
    !(x = NAG_ALLOC(npts, double)) ||
    !(xi = NAG_ALLOC(1, double)) ||
    !(isave = NAG_ALLOC(lisave, Integer)) )
{
    Vprintf("Allocation failure\n");
    exit_status = 1;
    goto END;
}
INIT_FAIL(fail);
exit_status = 0;
Vprintf("d03pxc Example Program Results\n");
/* Skip heading in data file */
Vscanf("%*[\n"]);
/* Problem parameters */
data.gamma = 1.4;
data.rlo = 5.99924;
data.rro = 5.99242;
data.ulo = 5.99924*19.5975;
data.uro = -5.99242*6.19633;
data.elo = 460.894/(data.gamma-1.0) + 0.5*data.rlo*19.5975*19.5975;
data.ero = 46.095 /(data.gamma-1.0) + 0.5*data.rro*6.19633*6.19633;
comm.p = (Pointer)
/* Initialise mesh */
for (i = 0; i < npts; ++i) x[i] = i/(npts-1.0);
/* Initial values */
for (i = 1; i <= npts; ++i)
{
    if (x[i-1] < 0.5)
    {
        U(1, i) = data.rlo;
        U(2, i) = data.ulo;
        U(3, i) = data.elo;
    } else if (x[i-1] == 0.5) {
        U(1, i) = 0.5*(data.rlo + data.rro);
        U(2, i) = 0.5*(data.ulo + data.uro);
        U(3, i) = 0.5*(data.elo + data.ero);
    } else {
        U(1, i) = data.rro;
        U(2, i) = data.uro;
        U(3, i) = data.ero;
    }
}
itrace = 0;
itol = 1;
atol[0] = 0.005;
rtol[0] = 5e-4;
xi[0] = 0.0;
ind = 0;
itask = 1;
for (i = 0; i < 30; ++i) algopt[i] = 0.0;
/* Theta integration */
algopt[0] = 2.0;
algopt[5] = 2.0;
algopt[6] = 2.0;

/* Max. time step */
algopt[12] = 0.005;

/* Read exact data at output points */
for (i = 1; i <= intpts; ++i)
{
    Vscanf("%lf", &UE(1,i));
    Vscanf("%lf", &UE(2,i));
    Vscanf("%lf", &UE(3,i));
}

/* Calculate density, velocity and pressure */
k = 0;
for (i = 15; i <= 127; i += 14)
{
    ++k;
    d = U(1, i);
    v = U(2, i)/d;
    p = d*(data.gamma-1.0)*(U(3, i)/d - 0.5*v*v);
    Vprintf(" %8.2e", x[i-1]);
    Vprintf(" %10.4e", d);
    Vprintf(" %10.4e", UE(1,k));
    Vprintf(" %10.4e", v);
    Vprintf(" %10.4e", UE(2,k));
    Vprintf(" %10.4e", p);
    Vprintf(" %10.4e\n", UE(3,k));
}

Vprintf("\n");
Vprintf(" Number of integration steps in time = %6ld\n", isave[0]);
Vprintf(" Number of function evaluations = %6ld\n", isave[1]);
Vprintf(" Number of Jacobian evaluations =%6ld\n", isave[2]);
Vprintf(" Number of iterations = %6ld\n", isave[4]);

END:
if (algopt) NAG_FREE(algopt);
if (atol) NAG_FREE(atol);
if (rtol) NAG_FREE(rtol);
if (u) NAG_FREE(u);
if (ue) NAG_FREE(ue);
if (rsave) NAG_FREE(rsave);
if (x) NAG_FREE(x);
if (xi) NAG_FREE(xi);
if (isave) NAG_FREE(isave);
return exit_status;
}

static void bndary(Integer npde, Integer npts, double t, const double x[],
const double u[], Integer ncode, const double v[],
const double vdot[], Integer ibnd, double g[],
Integer *ires, Nag_Comm *comm)
{
    struct user *data = (struct user *)comm->p;
    if (ibnd == 0)
    {
        g[0] = U(1, 1) - data->rlo;
        g[1] = U(2, 1) - data->ulo;
        g[2] = U(3, 1) - data->elo;
    } else {
        g[0] = U(1, npts) - data->rro;
        g[1] = U(2, npts) - data->uro;
        g[2] = U(3, npts) - data->ero;
    }
    return;
}

static void numflx(Integer npde, double t, double x, Integer ncode,
const double v[], const double uleft[],
const double uright[], double flux[], Integer *ires,
Nag_Comm *comm, Nag_D03_Save *saved)
{
    struct user *data = (struct user *)comm->p;
    NagError fail;
    Integer niter = 0;
    double tol = 0.0;
    INIT_FAIL(fail);
    d03pxc(uleft, uright, data->gamma, tol, niter, flux, saved, &fail);
    if (fail.code != NE_NOERROR)
    {
        Vprintf("Error from d03pxc.\n", fail.message);
    }
    return;
}

9.2 Program Data
d03pxc Example Program Data

9.3 Program Results
d03pxc Example Program Results

[NP3645/7] d03pxc.7
7.00e-01 1.4246e+01 1.4280e+01 8.6720e+00 8.6900e+00 1.6884e+03 1.6920e+03
8.00e-01 1.9214e+01 1.4280e+01 8.6742e+00 8.6900e+00 1.6892e+03 1.6920e+03
9.00e-01 3.0997e+01 3.1040e+01 8.6747e+00 8.6900e+00 1.6875e+03 1.6920e+03

Number of integration steps in time = 697
Number of function evaluations = 1708
Number of Jacobian evaluations = 1
Number of iterations = 2